

Yasser Mohammad

Principal Researcher Data Science Labs, NEC

Professor Assiut University, Egypt

Date of Birth: Sep. 7, 1976

Tokyo, Japan

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Interests

- Automated Negotiation
- 🞓 Time Series Data Mining
- Activity Recognition
- 🞓 Robotics and HRI

Short Bio

Yasser received his PhD from Kyoto University in 2009. Since then he worked in universities, national research institutes, research companies and industrial research laboratories. He collaborated with experts in psychology, computer science, mathematics, robotics, HCI, HRI, machine learning among other fields. His research spans the area of applied AI with a focus on robotics and multiagent systems. Author of two books and a hundred articles with over a thousand ciations. A senior IEEE member, PC member and reviewer for AAAI, IJCAI, AA-MAS, IROS, HRI, IEEE Trans. on System Man and Cybernetics, Social Robotics, Applied Intelligence, among many others. Main organizer of the SCML@ANAC running yearly in conjunction of IJCAI.

Industrial Experience

Jan, 2020 – ongoing	Senior Research Scientist Data Science Laboratories NEC, Japan Conducting research and developing systems in the areas of multiagent systems and ML. Leading platform development and international cooperation in automated negotiation.
Feb, 2020 – ongoing	Specially Appointed ResearcherAIRC, AIST, JapanResearch in automatic negotiation specially preference elicitation.
August, 2020 – July 2021	Visiting ResearcherAIP, RIKEN, JapanResearch in automatic negotiation specially concurrent negotiation.
Nov, 2017 – Dec, 2019	ResearcherAIRC, AIST, JapanResearch in automatic negotiation.
Jun, 2017 – Nov, 2017	Data Science AdvisorXtrava (xtrava.co), USADeveloping innovative real-time machine learning systems for biosen- sor data analysis.
Nov, 2016 – Nov, 2017	Chief Research Engineer KDDI Research Inc. (kddi-research.jp) Japan Conducting state of the art research in human behavior understand- ing using machine learning techniques. Applying pattern recognition and deep learning techniques to time-series data mining.
Jan, 2007 – Mar 2009	Technical Executive OfficerAyonix Inc. (ayonix.com) JapanProduced the complete first version of Ayofa SDK (A face detection/recognition SDK). Managed the development team of all products in the company.
Apr, 2004 – Oct, 2005	DeveloperSCTU, Assiut Univ., EgyptDeveloped Assiut University Information Systems Internet Portal and designed software for university automation.

Academic Experience

Dec, 2022 – ongoing	Professor (currently on leave) A Teaching and conducting research in intelligent system pating in administrative efforts.	Assiut Univ., Egypt ms and partici-
Aug, 2016 – Dec, 2022	Associate Professor A Teaching and conducting research in computer and neering and participating in administrative efforts.	Assiut Univ., Egypt systems engi-
Oct, 2015 – Jun, 2016	Adjunct Professor E- Working as an Adjunct Assistant Professor for one Mechatronics and Robotics Engineering Department University of Science and Technology (E-JUST), Egyp	J UST Univ., Egypt e day/week at t, Egypt-Japan ot.
Sep, 2012 – Aug, 2014	JSPS Fellow R Conducting research in imitation learning and its a robotics.	Kyoto Univ., Japan applications in
Jul, 2011 – Dec, 2011	GCOE Postdoc Visiting Researcher Conducting research in the applied intelligence dept. in with Prof. T. Nishida.	Kyoto Univ., Japan n collaboration
Jan, 2010 – Aug, 2016	Assistant Professor A Teaching and conducting research in computer and neering and participating in administrative efforts.	Assiut Univ., Egypt systems engi-
Jun, 2005 – Dec, 2009	Teaching AssociateAAssisting in teaching courses to students of ElectricalMechanical Engineering and introductory Engineeringsupervising graduation-projects	Assiut Univ., Egypt al Engineering, ng courses and
Apr, 2000 – Jun, 2005	Teaching AssistantAAssisting in teaching courses to students of ElectricalMechanical Engineering and introductory Engineeringsupervising graduation-projects	Assiut Univ., Egypt al Engineering, ng courses and
Sep, 1999 – Apr, 2000	Teaching AssistantAAssisting in teaching courses to students of ElectricalMechanical Engineering and introductory Engineeringsupervising graduation-projects	Assiut Univ., Egypt al Engineering, ng courses and

Metrics



Profiles -



Languages

Arabic (Mother Tongue)

English (Fluent)

Japanese (Learning)

Personal

Yasser lives with his partner, a medical doctor, and three children in Tokyo since 2016.

Education

2006 – 2009	Ph.D. in Info Title: Autono Robots and	o <mark>rmatics (AI)</mark> omous Development Embodied Agents.	of Natural Inter	Kyoto Univ. Japan active Behavior for
	AI HRI	Unsupervised Lea	rning Time Se	eries Analysis
2001 – 2005	M.Sc. in Cor Title: Anubis	mputers and System a: A novel network a	ns Engineering uthentication pro	Assiut Univ. Egypt
	Computer	Security Network	Authentication	BAN Logic
1993 – 1998	B.Sc. in Elect Graduation drawing app	rical Engineering Project: Construct lications.	ion and control	Assiut Univ., Egypt of a 2D robot for
	Robotics	Automatic Control	Simulation	

Review and Editorial Duties publons profile

Journals	New Generation Computing, Social Robotics, IEEE Trans. on
	Systems Man and Cybernetics, IEEE Trans. on Industrial
	Electronics, Neurocomputing, AI & Society, Applied Intelligence,
	among many others
Conferences	AAAI, IJCAI, AAMAS, IEEE ROMAN, IEEE HRI, IEEE IROS, DATA,
	IEA/AIE, ISIEA, PECON, ACHI, ICCCI, ICAS, KUI,
Organizer	SCM league of the ANAC competition in conjunction with IJCAI
	since 2019

Honours and Awards

Dec 2023	Best Paper Award The 7th IEEE International Conference on Ag	Kyoto, Japan ents (IEEE ICA)
Jan 2021	Finalist for the International Automated Neg petition (Genius track) International Joint Conference on Artificial In	gotiating Agents Com - Nagoya, Japan Itelligence (IJCAI)
Nov 2020	Runner for Best Paper Award The 23rd International Conference on Princ Multi-Agent Systems (PRIMA)	Nagoya, Japan ciples and Practice of
Mar 2015	Best Presentation Award the 3rd International Conference on Industria ing	Kitakyush, Japan I Application Engineer-
Sep 2014	Outstanding Paper Award ICROS International Conference on Control, Au (ICCAS) 2014 (out of 337 accepted papers fi	Seoul, South Korea Itomation and Systems rom 25 countries)
Sep 2012	JSPS Fellowship JSPS long term post-doc fellowship for foreig 2014)	Kyoto University, Japan gn researchers (2012-
Jul 2011	GCOE Postdoc Fellowship July-December 2011	Kyoto University, Japan
Oct 2011	Best Paper Award IEEE SII 2012 (Control) (from 248 accepted	Kitakyush, Japan papers)
Jun 2009	Best Paper Award the Twenty Second International Conference I and other applications of Applied Intelligent Sy Acceptance rate was 29% out of 286 submitte among top 701 computer science conference	Tainan, Taiwan Industrial, Engineering, Industrial, Engineering, Industrial, Engineering, Industrial States Industrial S
Jun 2008	Best Paper Award the Twenty First International Conference Ir and other applications of Applied Intelligent Sy Acceptance rate was 30% out of 270 submitte among top 701 computer science conference	Wroclaw, Poland ndustrial, Engineering, vstems (IEA/AIE 2008). ed papers (ranked 46th es)

Teaching Experience

Undergradute Courses (Partial List)

Assiut University	Electrical Engineering 2010–2015 Introduction to Computer Science, Numerical Analysis, Micropro- cessors, Computer Organization, Computer Architecture, Database Systems, Digital Signal Processing, Databases
Assiut University	Mechatronics2010–2015Robotics Engineering2010–2015
Assiut University	Information and Computers 2010–2015 Graphical User Interfaces, Network Security, Computer Security, Microprocessors, Computer Organization
Postgraduat	e Courses (Partial List)
E-JUST University	Mechatronics Engineering M.sc. and PhD2016Intelligent Control Systems2016
Assiut University	Electrical Engineering M.sc. and PhD 2010–2015 Robot Motion Planning, Pattern Recognition, Probabilistic Inference, Data Sciences and BigData
Academic S	upervision
2012–2016	Mostafa Abdallah M.Sc., AUN, Egypt An Integrated ROS stack for Autonomous learning of Perceptual and Motion Primitives
2015–2020	Yomna MohammadM.Sc., AUN, EgyptPattern Discovery in Time Series
2019–2022	Niang Yo M.Sc., Fraunhofer, ISC, Germany Design of AI agent for Supply Chain Management using Deep Rein- forcement Learning
2019–2022	Alyaa SabraM.Sc., AUN, EgyptFeature Selection for Face Recognition
2019–2022	Zaynab AshrafM.Sc., AUN, EgyptText Mining tool for Genome Scale Metabolic Model
2021-	Abdallah AhmedM.Sc., EJUST, EgyptDeep Learning for Robot Navigation in Dynamic Environments

Funded Projects

May 2014 Investigator Japan	Theoretical Framework for Interactive Game Design >10M JPY Aerospace Research and Development (AFOSR/AOARD) To estab- lish a theoretical framework for achieving content-rich, proficient and reliable communication between people and robots.
Sep 2012	Fluid Imitation Learning 2.5M JPY
PI	Japanese Society for Promotion of Science To design, implement
Japan	fluid imitation by autonomously discovering interesting motions to imitate during its interaction with humans.
Nov 2008	Grounded Action Segmentation and Association 1M JPY
PI	Global Centre of Excellence Young Researcher Program, Kyoto Uni-
Japan	versity To build and evaluate an unsupervised algorithm for learning
	interactive behavior both in implicit and explicit nonverbal communi- cation settings.
Dec 2007	Natural Listening for a Humanoid Robot 1.5M JPY
PI	Global Centre of Excellence Young Researcher Program, Kyoto
Japan	University To design and implement a learning system that can
	help the robot achieve natural listening behavior in an automatic way.

References

Brown Univ.,	Amy Greenwald	Professor	
USA	amy_greenwald@brown.edu		
MIT, USA	Mark Klein m_klein@mit.edu	Senior Research Scientist	
Fukuchiyama Univ., Japan	Toyoaki Nishida toyoaki.nishida@fukuchiyama.ac.jp	Dean of the Faculty of Informatics	

Patents

ng USA 2022 Jotiation support using	Negotiation method including elicitation and system for implementing A system for negotiation under uncertainty with elicitation-during-nego Value of Information concept (50%)	US17/388,004 Application
Japan 2021 works to achieve high	Learning data generator, judgment device and program A method for training multiple pipelines of convolutional neural netw accuracy in activity recognition (90%)	IP6838259B2 Granted
Japan 2020 rwise) based on novel	Neural network regulators, devices and programs A method for compression neural networks (convolutional or otherw application of feature selection techniques (90%)	IP6754343B2 Granted
USA 2021 gotiation domains and	Adaptive Autonomous Negotiation Method and System of Using A new automated negotiation method that can generalize along nego opponents (30%)	US17/184,590 Application
γ Computer-Readable PCT 2020 opponents with static	Policy Generation Apparatus, Control Method, and Non Transitory Storage Medium A method for concurrent negotiation proven to be optimal against o acceptance models (100%).	PCT/JP2020- D29145 Application

Publications and Talks

Tutorials

- 1. **[2023]** Automated Negotiation in Supply Chains, **Yasser Mohammad**, IEEE International Conference on Agents (ICA), Kyoto, Japan.
- 2. [2023] Reinforcement Learning for Automated Negotiation, Yasser Mohammad, Australasian Joint Conference on Artificial Intelligence (AJCAI), Brisbane, Australia.
- 3. [2022] Automated Negotiation: Challenges and Tools, Yasser Mohammad and Amy Greenwald, The 36th AAAI Conference on Artificial Intelligence, Vancouver, Canada
- 4. **[2020]** Automated Negotiation in Supply Chain Management, **Yasser Mohammad**, The 23nd International Conference on Principles and Practice of Multi-Agent Systems, Nagoya, Japan
- 5. [2019] Automated Negotiation: Challenges and Tools, Yasser Mohammad, The 22nd International Conference on Principles and Practice of Multi-Agent Systems, Torino, Italy

Invited Talks

- 6. **[2022]** Generalized Bargaining Mechanisms: Mechanism Design for Automated Negotiation, IBM/DIMACS Workshop on Bridging Game Theory and Machine Learning for Multi-party Decision Making, October 27-28, New Jersey, USA.
- 7. [2022] Concurrent Negotiation in Supply Chains: Problems, Solutions and Challengs, The 13th International Workshop on Agent-based Complex Automated Negotiations in conjunction with the 31st International Joint Conference on Artificial Intelligence, Vienna, Austria.
- 8. [2018] Analysis and commentary on PRIANAC and ANAC, Pacific Rim International Automated Negotiation Agents Competition (PRIANAC) in conjunction with PRIMA, Tokyo, Japan.
- 9. **[2018]** Fluid Imitation, Human-Robot Interaction: From Service to Industry (HRI-SI2018) part of IEEE ROMAN 2018, Nanjing, China.
- 10. [2012] SSA application to motif discovery and causality analysis in robotics, Third International Conference on SSA and its applications, Beijing, China, May 17th-May 20th.

Books

- 11. [2016] Yasser Mohammad and Toyoaki Nishida, Data Mining for Social Robotics, Springer, ISBN 978-3-319-25230-8.
- 12. **[2014]** T. Nishida, A. Nakazawa, Y. Ohmoto, **Y. Mohammad**, Conversational Informatics: A data intensive approach with emphasis on Nonverbal Communication, Springer, ISBN 978-4431550396.

International Journals

- [2023] An octopamine receptor involved in feeding behavior of the two-spotted spider mite, Tetranychus urticae Koch: a possible candidate for RNAi-based pest contro, Faten Abdelsalam Hamdi, Kosuke Kataoka, Yuka Arai, Naoki Takeda, Masanobu Yamamoto, Yasser F. O. Mohammad, Noureldin Abuelfadl Ghazy, Takeshi Suzuki, Entomologia Generalis, February 9th, 2023
- 14. **[2022]** Optimal Time-based Strategy for Automated Negotiation, **Yasser Mohammad** and Shinji Nakadai, Applied Intelligence, July, 2022.
- 15. **[2021]** Concurrent Local Negotiations with a Global Utility Function: A Greedy Approach, **Yasser Mohammad**, Autonomous Agents and Multiagent Systems, 35(28).
- 16. **[2020]** Supply Chain Management League(SCML) Automated Negotiating Agent Competition for Manufacturing Value Chain, **Yasser Mohammad**, Shinji Nakadai, Satoshi Morinaga, Katsuhide Fujita, JSAI Journal Vol 35 No 3, May 2020

- 17. **[2019]** Selecting orientation-insensitive features for activity recognition from accelerometers, **Mohammad, Y.**, Matsumoto, K., Hoashi, K. IEICE Transaction on Information and Systems, 102(1), 104-115.
- 18. [2018] Primitive activity recognition from short sequences of sensory data, Y. Mohammad, K Matsumoto, K Hoashi Applied Intelligence,
- 19. **[2016]** Exact multi-length scale and mean invariant motif discovery, **Yasser Mohammad** and Toyoaki Nishida, Applied Intelligence, vol.44, no.2, pp. 322-339, March
- 20. **[2015]** Learning interaction protocols by mimicking: Understanding and reproducing human interactive behavior, **Yasser Mohammad** and Toyoaki Nishida, Pattern Recognition Letters, vo. 66, no. 15, pp. 62-70, November
- 21. **[2015]** Why should we imitate robots? Effect of back imitation on judgment of imitation skill, **Yasser Mohammad** and Toyoaki Nishida, International Journal on Social Robotics, vol.7, no.4, pp. 497-512, August
- 22. **[2015]** Shift Density Estimation based Approximately Recurring Motif Discovery, **Yasser Mohammad** and Toyoaki Nishida, International Journal of Applied Intelligence, vol. 42, no. 1, pp. 112-134, January
- 23. [2013] Learning where to look: Autonomous Development of Gaze Behavior for Natural Human-Robot Interaction, Yasser Mohammad and Toyoaki Nishida, International Journal of Interaction Studies, Springer, no. 32, pp. 419-450, .
- 24. **[2012]** Fluid Imitation: Learning from Unplanned Demonstrations, **Yasser Mohammad** and Toyoaki Nishida, International Journal of Social Robotics, vol. 4, pp 369-382,
- 25. **[2010]** Using Physiological Signals to Detect Natural Interactive Behavior, **Yasser Mohammad** and Toyoaki Nishida, Applied Intelligence, vol. 13, no. 1, pp. 79-92,
- 26. **[2010]** Controlling Gaze with an Embodied Interactive Control Architecture, **Yasser Mohammad** and Toyoaki Nishida, International Journal of Applied Intelligence, Vol. 32, No. 2, pp 148-163,
- 27. [2009] Constrained Motif Discovery in Time Series, Yasser Mohammad and Toyoaki Nishida, New Generation Computing Journal, vol. 27, pp. 319-346,
- 28. **[2009]** Towards Combining Autonomy with Interaction for Social Robots, **Yasser Mohammad** and Toyoaki Nishida, AI & Society, vol. 24, no. 1, pp 35-53,
- 29. **[2009]** Interactive Perception for amplification of intended behavior in complex noisy environment, **Yasser Mohammad** and Toyoaki Nishida, AI & Society Journal, vol. 23, no. 2, pp 167-186, March
- [2008] Interaction Between Untrained Users and a Miniature Robot in a Collaborative Navigation Controlled Experiment, Yasser Mohammad and Toyoaki Nishida, International Journal of Information Acquisition, World Scientific Publishing Company. Vol. 5, No. 4, pp 291-308, April
- 31. [2006] Towards Robots as an Embodied Knowledge Medium, Toyoaki Nishida, Kazunori Terada, Takashi Tajima, Makoto Hatakeyama, Yoshiyasu Ogasawara, Xu Yong, Yasser Mohammad, Kateryna Tarasenko, Taku Ohya, and Tatsuya Hiramatsu, IEICE Trans. On Inf. & Sys., vol. E89-D, No 6, pp. 1768-1780, June

International Conferences

- 32. **[2023]** Evaluating Automated Negotiations, **Yasser Mohammad**, IEEE International Conference on Agents (ICA), December 2023, Kyoto, Japan [Best Paper Award].
- 33. **[2023]** Generalized Bargaining Protocols: Mechanism Design for Automated Negotiations, **Yasser Mohammad**, Australasian Joint Conference on Artificial Intelligence, November 2023, Brisbane, Australia.
- 34. **[2022]** End-to-End Mobile Robot Navigation using a Residual Deep Reinforcement Learning in Dynamic Human Environments, Abdullah Ahmed, **Yasser Mohammad**, Victor Parque, Haitham El-Hussieny and Sabah Ahmed, 18th IEEE/ASME International Conference on Mechatronic, Embedded Systems and Applications (MESA), November 2022, Taipei, Taiwan
- 35. **[2022]** Transfer Learning based Adaptive Automated Negotiating Agent Framework, Ayan Sengupta, **Yasser Mohammad**, Shinji Nakadai, The 31st International Joint Conference on Artificial Intelligence (IJCAI 2022), pp. 1163–1172, July 2022, Vienna, Austria
- 36. **[2022]** Concurrent Negotiations with Local Utility Functions , **Yasser Mohammad**, Shinji Nakadai, The 21st International Conference on Autonomous Agents and Multiagent Systems (AAMAS), London, UK, May.
- [2022] Applying Generative Adversarial Networks and Vision Transformers in Speech Emotion Recognition, Panikos Heracleous, Satoru Fukayama, Wei Yang, Jun Ogata, Yasser Mohammad, 24th International Conference on Human-Computer Interaction (HCI 2022 International), June 26 – July 1st, Cothernbury, Sweden.
- [2021] An Autonomous Negotiating Agent Framework with Reinforcement Learning Based Strategies and Adaptive Strategy Switching Mechanism, Ayan Sengupta, Yasser Mohammad, Shinji Nakadai, The 20th International Conference on Autonomous Agents and Multiagent Systems (AAMAS), London, UK, May.
- 39. **[2021]** Speech Emotion Recognition Using Combined Multiple Pairwise Classifiers, Panikos Heracleous, **Yasser Mohammad**, Akio Yoneyama, 22nd International Conference On Human-Computer Interaction, Copenhagen, July.
- 40. **[2020]** Optimal Deterministic Time-dependent Policy in Automated Negotiation, **Yasser Mohammad**, The 23rd International Conference on Principles and Practice of Multi-Agent Systems (PRIMA), Nagoya, Japan, November [Best Paper Runner].
- 41. **[2020]** NegMAS: A platform for Automated Negotiations, **Yasser Mohammad**, Shinji Nakadai, and Amy Greenwald, The 23rd International Conference on Principles and Practice of Multi-Agent Systems (PRIMA), Nagoya, Japan, November.
- 42. **[2020]** Integrating Language and Emotion Features for Multilingual Speech Emotion Recognition, Panikos Heracleous, **Yasser Mohammad**, Akio Yoneyama, 22nd International Conference On Human-Computer Interaction, Copenhagen, Denmark, July.
- 43. **[2020]** An Empirical Study On Feature Extraction In DNN-Based Speech Emotion Recognition, Panikos Heracleous, Kohichi Takai, Yanan Wang, Keiju Yasuda, Akio Yoneyama, **Yasser Mohammad**, 22nd International Conference On Human-Computer Interaction, Copenhagen, Denmark, July.
- 44. **[2019]** Empirical Mechanism Design under Uncertainty, Enrique Areyan Viqueira, Amy Greenwald, **Yasser Mohammad**, Uncertainty in AI.
- 45. **[2019]** Research Challenges for the Automated Negotiating Agents Competition (ANAC), Reyhan Aydoğan, Tim Baarslag, Katsuhide Fujita, Johnathan Mell, Jonathan Gratch, Dave De Jonge, **Yasser Mohammad**, Shinji Nakadai, Satoshi Morinaga, Hirotaka Osawa, Claus Aranha and Catholijn Jonker, EUMAS AT 2020
- 46. **[2019]** Optimal Value of Information Based Elicitation During Negotiation, **Yasser Mohammad** and Shinji Nakadai, AAMAS, Montreal, Canada pp. 242-250
- 47. **[2019]** Multidimensional Permutation Entropy for Constrained Motif Discovery, Yomna Rayan, Yasser F. O. Mohammad, Samia A. Ali, ACIIDS 231-243

- 48. **[2019]** Speech emotion recognition using spontaneous children's corpus, Heracleous P., **Mohammad Y.**, Yasuda K., Yoneyama A., CICLing 2019, La Rochelle, France, April.
- [2018] Comparative Study on Spoken Language Identification Based on Deep Learning, Heracleous, P., Takai, K., Yasuda, K., Mohammad, Y., and Yoneyama, A., In 2018 26th European Signal Processing Conference (EUSIPCO) (pp. 2265-2269). IEEE.
- 50. **[2018]** Deep feature learning and selection for activity recognition, (, April), **Y. Mohammad**, K. Matsumoto, K. Hoashi, In Proceedings of the 33rd Annual ACM Symposium on Applied Computing (pp. 930-939). ACM.
- 51. **[2018]** FastVOI: Ecient Utility Elicitation During Negotiations, **Yasser Mohammad** and Shinji Nakadai, PRIMA, October 2018, Tokyo, Japan
- 52. **[2018]** Utility Elicitation During Negotiation with Practical Elicitation Strategies, **Yasser Mohammad** and Shinji Nakadai, IEEE International Conference on Systems, Man, and Cybernetics (IEEE SCM), Miyazaki, Japan, October 7-10.
- [2018] Deep feature learning and selection for activity recognition, Yasser Mohammad, Kazunori Matsumoto, and Keiichiro Hoashi, In Proceedings of the 33rd Annual ACM Symposium on Applied Computing (SAC '18), pp. 930-939, New York, NY, USA, .
- 54. **[2018]** Comparative Study on Spoken Language Identification Based on Deep Learning, Panikos Heracleous, Kohichi Takai and Keiji Yasuda, **Yasser Mohammad**, Akio Yoneyama, 26th European Signal Processing Conference (EUSIPCO), Rome, Italy, September 3-7, 2018
- 55. **[2018]** I-vectors and Deep Convolutional Neural Networks for Language Identification in Clean and Reverberant Environments, Panikos Heracleous, **Yasser Mohammad**, Akio Yoneyama, International Conference on Computational Linguistics and Intelligent Text Processing (CICLing), March 18 to 24, • Hanoi, Vietnam
- [2018] Spoken Language Identification Based on I-vectors and Conditional Random Fields, Panikos Heracleous, Yasser Mohammad, Akio Yoneyama, 14th International Wireless Communications and Mobile Computing Conference IWCMC, Limassol, Cyprus, June 25-29, 2018
- 57. **[2017]** A dataset for activity recognition in an unmodified kitchen using smart-watch accelerometers, **Yasser Mohammad**, Kazunori Matsumoto, and Keiichiro Hoashi, In Proceedings of the 16th International Conference on Mobile and Ubiquitous Multimedia (MUM '17). ACM, New York, NY, USA, 63-68, .
- [2017] COLD: A ROS Package for Continuous Learning from Demonstration: teaching a robot to write, Mostafa Hussein, Yasser Mohammad, Samia Ali, Toyoaki Nishida, IEEE International Conference on Mechatronics and Automation ICMA, pp. 651-657, Takamatsu, Japan,
- 59. **[2016]** MC2: An integrated toolbox for change, causality, and motif discovery, **Yasser Mohammad** and Toyoaki Nishida, IEA/AIE, August , pp. 128-141, Morioka, Japan
- [2015] Learning From Demonstration Using Variational Bayesian Inference, Mostafa Hussein, Yasser Mohammad, and Samia A. Ali, First International Conference on Industrial, Engineering & Other Applications of Applied Intelligent Systems IEA/AIE, pp. 371-381, Seool, Korea,
- 61. [2015] Synthetic Evidential Study as Augmented Collective Thought Process Preliminary Report, Toyoaki Nishida, Masakazu Abe, Takashi Ookaki, Divesh Lala, Sutasinee Thovuttikol, Hengjie Song, Yasser Mohammad, Christian Nitschke, Yoshimasa Ohmoto, Atsushi Nakazawa, Takaaki Shochi, Jean-Luc Rouas, Aurelie Bugeau, Fabien Lotte, Zuheng Ming, Geoffrey Letournel, Marine Guerry and Dominique Fourer, 7th Asian Conference on Intelligent Information and Database systems (ACIIDS), pp. 13-22, Indonesia,
- 62. **[2015]** Simple Incremental GMM Modeling using Multidimensional Piecewise Linear Segmentation for Learning from Demonstration, **Yasser Mohammad** and Toyoaki Nishida, 3rd International Conference on Industrial Application Engineering (ICIAE), Japan, **(Best Presentation Award)**
- 63. [2014] Robust Learning from Demonstrations using Multidimensional SAX, Yasser Mohammad and Toyoaki Nishida, International Conference on Control, Automation, and Systems, pp. 64-71, Korea (September 22-26, 2014), (Outstanding Paper Award)
- [2014] Scale Invariant Molti-length Motif Discovery, Yasser Mohammad and Toyoaki Nishida, The 27th International Conference on Industrial, Engineering and Other Applications of Applied Intelligent Systems, pp. 417-426, Kaohsiung, Taiwan,
- 65. **[2014]** Exact Motif Discovery of Length-Range Motifs, **Yasser Mohammad**, Toyoaki Nishida, and Atsushi Nakazawa, The 6th Asian Conference on Intelligent Information and Database Systems (ACIIDS), pp. 23-32, Bangkok, Thailand
- 66. **[2014]** Why shoold we imitate robots?, **Yasser Mohammad** and Toyoaki Nishida, 13th International Conference on Autonomous Agents and Moltiagents Systems (AAMAS), pp. 1499-1500, [extended abstract]
- 67. **[2014]** A joint activity theory analysis of body interactions in moltiplayer virtual basketball, Divesh Lala, **Yasser Mohammad**, Toyoaki Nishida, Proceedings of the 28th International BCS Human Computer Interaction Conference on HCI, pp. 62-71, .
- [2014] Detection of Hidden Laughter for Human-agent Interaction, Shiho Tatsumi, Yasser Mohammad, Yoshimasa Ohmoto, Toyoaki Nishida, Knowledge-Based and Intelligent Information & Engineering Systems 18th Annual Conference, pp. 1053-1062 Gdynia, Poland, September 15-17,
- 69. **[2013]** Arm Pose Copying for Humanoid Robots, **Yasser Mohammad**, Toyoaki Nishida, and Atsushi Nakazawa, IEEE International Conference on Robotics and Biomimetics, ROBIO, Shenzhen, China, 2013
- 70. **[2013]** Unsupervised gesture recognition system for learning manipolative actions in virtual basketball, Divesh Lala, Toyoaki Nishida, and **Yasser Mohammad**, International Conference on Human-Agent Interaction iHAI, pp. II-1-3,
- 71. **[2013]** Tackling the Correspondence Problem: Exact solution for a Humanoid Upper Body?, **Yasser Mohammad**, Toyoaki Nishida, International Conference on Active Media Technology , pp. 84-95, Maebashi, Japan, 2013
- 72. **[2013]** Approximately Recurring Motif Discovery Using Shift Density Estimation, **Yasser Mohammad**, Toyoaki Nishida, International Conference on Industrial, Engineering, Other Applications of Applied Intelligent Systems IEA/AIE, pp. 141-150, 2013
- 73. **[2013]** Learning Sensorimotor Concepts Without Reinforcement, **Yasser Mohammad**, Toyoaki Nishida, AAAI Summer Symposium on Life Long Machine Learning , Stanford, USA
- 74. **[2012]** Unsupervised Discovery of Basic Human Actions from Activity Recording Datasets, **Yasser Mohammad**, Toyoaki Nishida, IEEE/SICE International Symposium on System Integration, pp. 402-409, Kyushu, Japan,
- 75. **[2012]** Self-Initiated Imitation Learning Discovering what to imitate, **Yasser Mohammad**, Toyoaki Nishida, International Conference on Control, Automation and Systems , pp. 726-732, Jeju, South Korea, 2012
- 76. **[2012]** G-SteX: Greedy Stem Extension for Free-Length Constrained Motif Discovery, **Yasser Mohammad**, Toyoaki Nishida, International Conference on Industrial, Engineering, Other Applications of Applied Intelligent Systems IEA/AI, pp. 417-426,

- 77. [2012] Common Sensorimotor Representation for Self-Initiated Imitation Learning, Yasser Mohammad, Toyoaki Nishida, International Conference on Industrial, Engineering, Other Applications of Applied Intelligent Systems IEA/AIE, pp. 381-390,
- 78. **[2012]** CPMD: A Matlab Toolbox for Change Point and Constrained Motif Discovery, **Yasser Mohammad**, Toyoaki Nishida, International Conference on Industrial, Engineering, Other Applications of Applied Intelligent Systems IEA/AIE, pp. 114-123,
- 79. [2011] Discovering Causal Change Relationships Between Processes in Complex Systems, Yasser Mohammad, Toyoaki Nishida, IEEE/SICE International Symposium on System Integratio, pp. 12-17,
- 80. **[2011]** On Comparing SSA-based Change Point Discovery Algorithms, **Yasser Mohammad**, Toyoaki Nishida, IEEE/SICE International Symposium on System Integration, pp. 938-945, **(Best Paper Award)**
- 81. **[2010]** Incremental Gesture Discovery for Interactive Robots, **Yasser Mohammad**, Toyoaki Nishida, IEEE International Conference on Robotics and Biomimetics ROBIO , pp. 185-189, Tianjin, China,
- [2010] Learning Interaction Protocols using Augmented Bayesian Networks Applied to Guided Navigation, Yasser Mohammad, Toyoaki Nishida, Taipei, Taiwan, IEEE/RSJ International Conference on Intelligent Robots and Systems IROS, pp. 4119-4126,
- 83. **[2010]** Learning Spontaneous Nonverbal Behavior using a Three Layers Hierarchy, **Yasser Mohammad**, Toyoaki Nishida, 10th WSEAS International Conference on Applied Computer Science, pp. 430-435, Iwate, Japan, October
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